

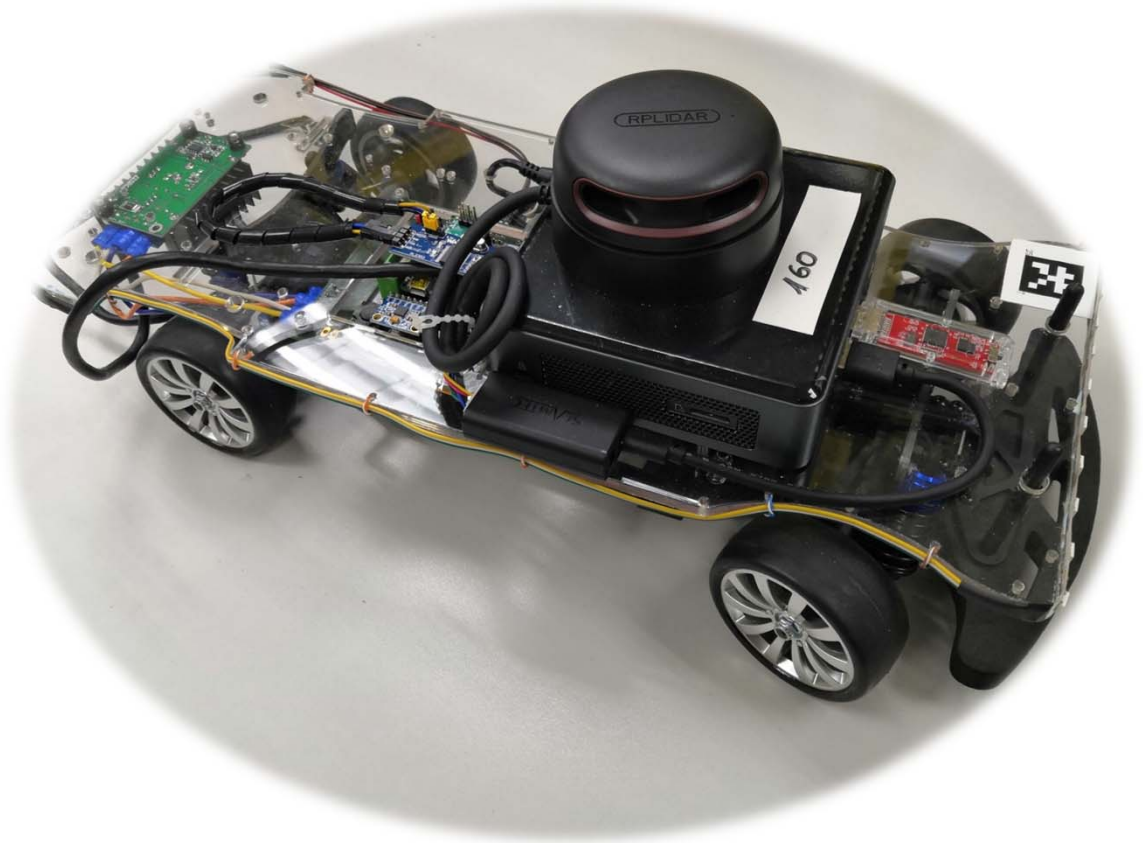
Autonomous Car

Autominy

Dr. Roger Miranda

Colorado

Setting up the Autominy car



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Setting up the Autominy car

After installing the **Autominy package**, we can make a first test with the simulator. To this end, we can use the next command:

1. `$ roslaunch autominy Simulated.launch`

- Then, we obtain an environment where we can make some tests with the **simulated Autominy car**.
- All the **topics** from the real vehicle are available in the simulator.
- We can use the topics to make the vehicle to move.
- We can design some programs to control the autonomous car.

Setting up the Autominy car

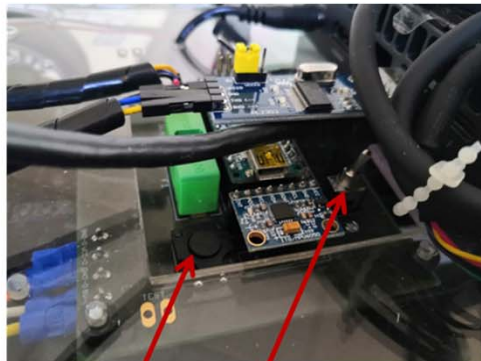
The following video shows how to use the simulator for controlling the autonomous vehicle.



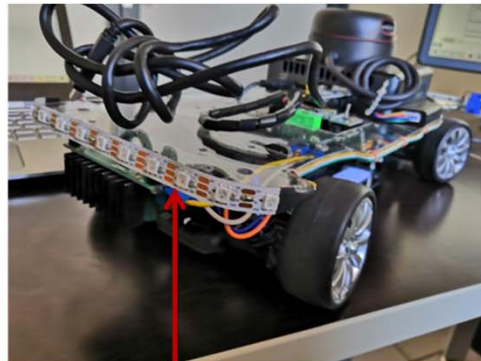
Setting up the Autominy car

Now, for the real vehicle, we can follow the next steps to **start up the car**:

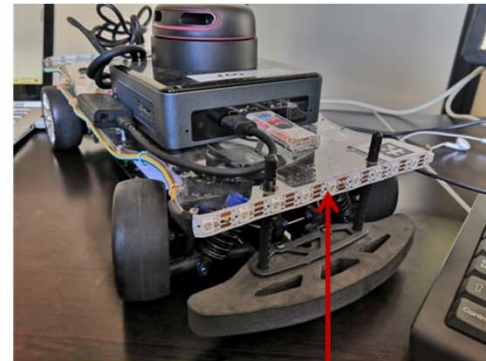
1. Switch the lever pointing towards the back of the car.
2. Press the start button for at least 3 seconds.



Push button
Lever



Back LEDs

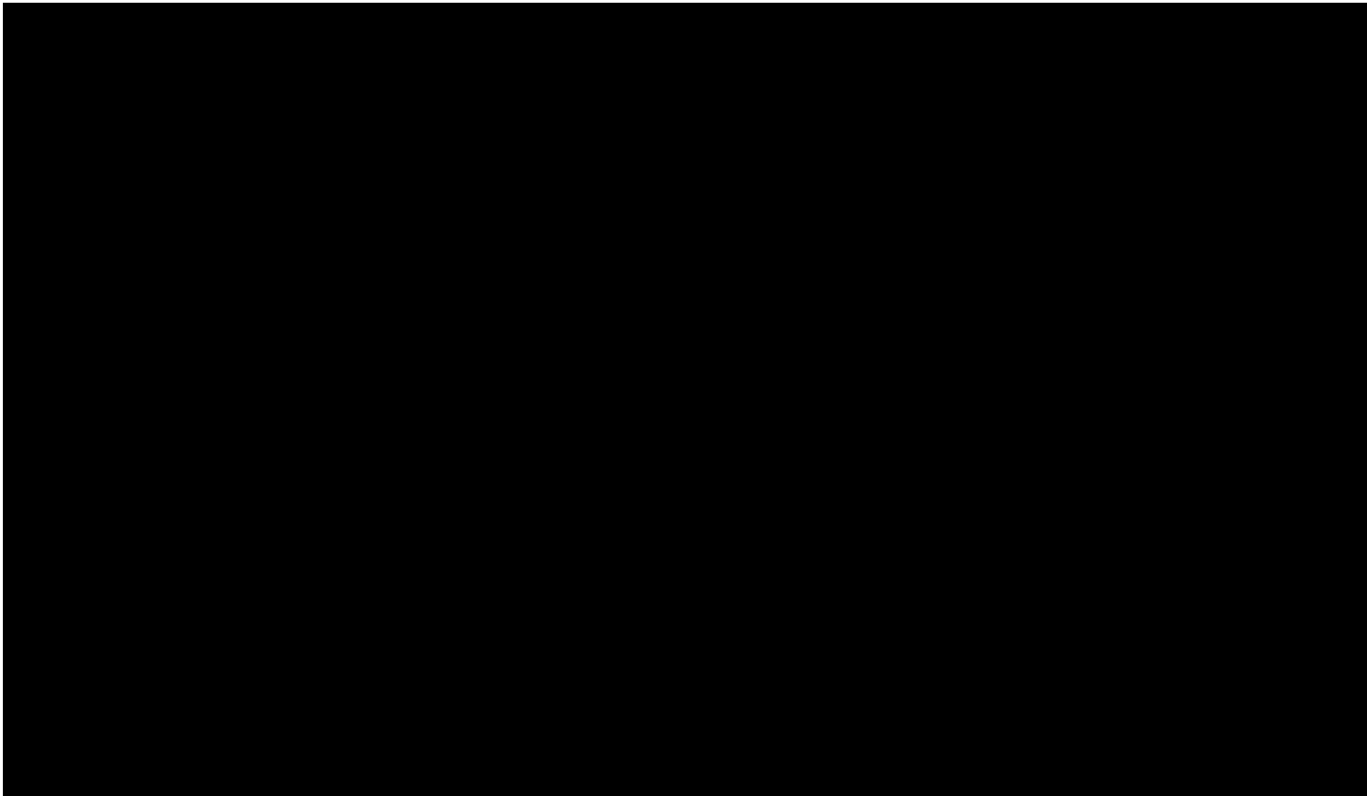


Rear LEDs

- Then, the car turns on, shows the battery level through the LEDs (rear and back).
- **Green**, **yellow**, and **red** for voltage above **14.8 V**, between **13-14.8 V**, and below **13 V**, respectively. Turns off if voltage is below 12.8 V. **The voltage tester may begin buzzing!**

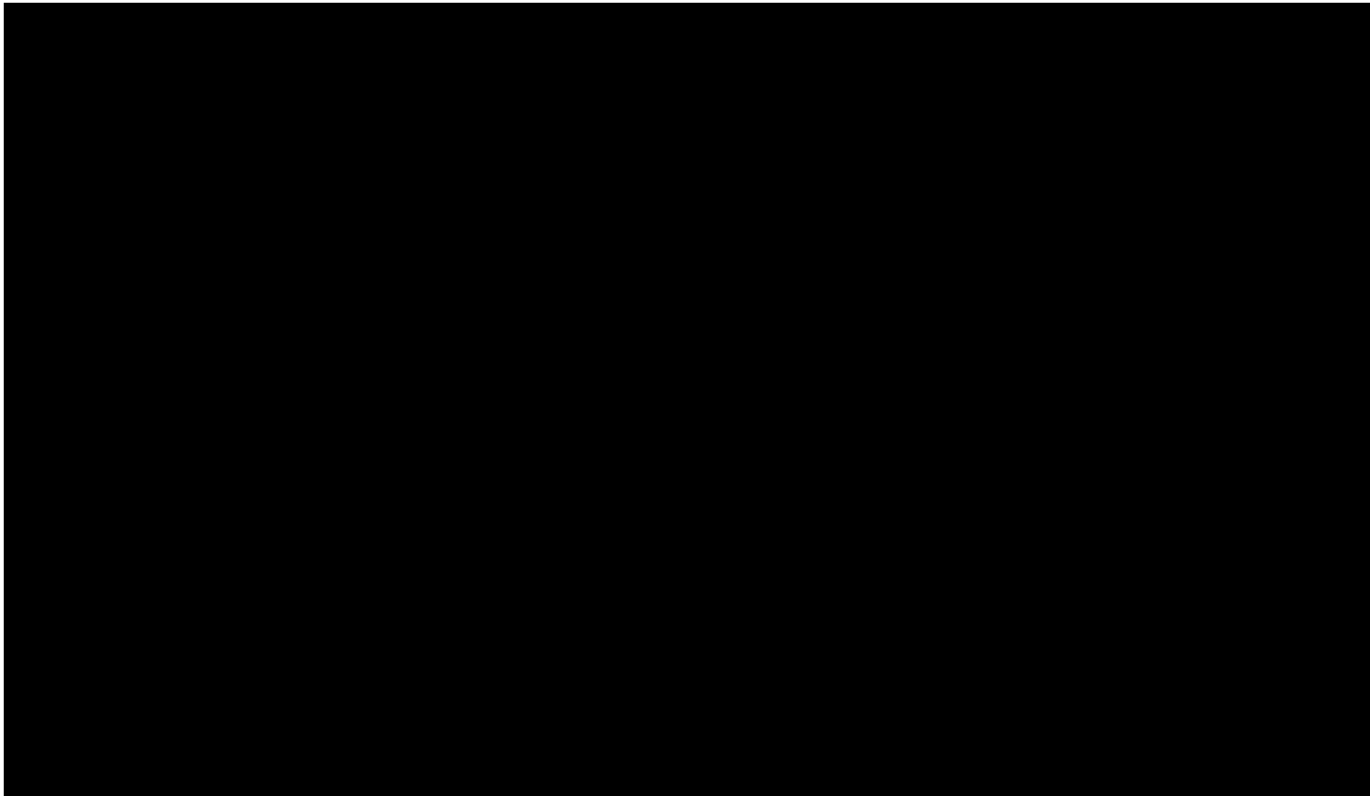
Setting up the Autominy car

3. After turning on, it takes about 30 s for the NUC to boot. Then, the car's software starts up and the LIDAR starts spinning.

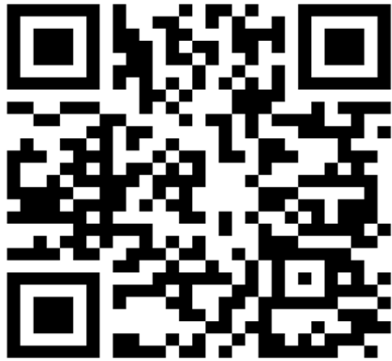


Setting up the Autominy car

4. After turning on the car, we can make some tests on the actuators, i.e., we connect our computer to the car and send some commands to make it to move.



Dr. Roger Miranda Colorado



Researchgate:
<https://www.researchgate.net/profile/Roger-Miranda-Colorado-2>

Google Scholar:
https://scholar.google.com/citations?hl=es&user=NmzkrSwAAAAJ&view_op=list_works&sortby=pubdate

Pure-IPN:
<https://ipn.elsevierpure.com/es/persons/roger-miranda-colorado-3>

Youtube:
<https://www.youtube.com/channel/UCeGT1IfNnJt695XGzEI4IXA>

